

## Drag, morphology and mechanical properties of three species of octocorals

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### Abstract

Drag force, morphology and mechanical properties of three *Sarcophyton* species, *S. buitendijki* Verseveldt, *S. cinereum* Tixier–Durivault and *S. crassocaule* Moser were studied. Among the three species, *S. buitendijki* has the highest flexibility and lowest stiffness that enable them to bend into a drag-reducing orientation by collapsing the colony and lying near the substratum at higher velocities. *S. cinereum* has intermediate flexibility and stiffness; deformation of the colony does not result in the reduction of drag forces, it resists drag forces by stiffness. Colonies of *S. crassocaule* have the highest stiffness which allows them to retain streamlining. They reduce drag forces by staying in the lower-velocity boundary layer. This study shows that the three sympatric *Sarcophyton* species possess different morphological and mechanical properties and they coexist in the same environment by adopting different strategies to reduce drag forces.

*Keywords:* Alcyonacea; Biomechanics; Drag; Morphology; Water flow

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### 1. Introduction

Fluid flow is an important environmental factor acting upon sessile organisms (Koehl, 1982a). These organisms depend on moving water to bring them food and to carry away wastes, but they also risk being dislodged or broken by fluid flow (Koehl, 1984; Denny et al., 1985; Denny, 1988). A fluid moving relative to an organism imposes mechanical forces upon that organism. These forces, which tend to carry the organism downstream, are known as drag forces (Wainwright et al., 1976; Vogel, 1981).

Drag force is an important factor influencing the morphology and mechanical

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properties of sessile organisms (Rees, 1972; Chamberlain and Graus, 1975; Velimirov, 1976). Sessile organisms, such as octocorals, require hydrodynamic adaptations to reduce the effect of drag forces (Wainwright and Dillon, 1969; Grigg, 1972; Jackson, 1979; Patterson, 1980). The morphology and behaviour of these animals also affect the flow patterns and drag forces they encounter (Sponaugle, 1991; Abelson et al., 1993; Dai and Lin, 1993).

Alcyonacean corals are among the most abundant sessile organisms on many Indo-Pacific coral reefs (Benayahu and Loya, 1977; Dinesen, 1983; Dai, 1993). They commonly exist on the reefs exposed to currents and storm disturbances (Dai, 1991). Hydrodynamic conditions may play an important role in determining the distribution of alcyonacean corals.

Alcyonacean corals exhibit remarkable plasticity with respect to colony shape and mechanical properties of tissues (Patterson, 1980; Koehl, 1982b). *Sarcophyton* species demonstrate a great variety in morphological and structural diversity (Verseveldt, 1982). However, the variations in morphology and mechanical properties of these organisms as a function of water movement are little investigated. We conducted a comparative assessment relating the morphology and mechanical properties of three *Sarcophyton* species to the drag forces they encountered under various flow velocities.

## 2. Materials and methods

### 2.1. Specimen collection and acclimation

Colonies of three *Sarcophyton* species, *S. buitendijki* Verseveldt, *S. cinereum* Tixier-Durivault and *S. crassocaule* Moser were collected from the coral reef in Nanwan Bay, southern Taiwan (120°44' E, 21°57' N). Species identifications followed Verseveldt (1982). Colonies of *S. cinereum* and *S. buitendijki* are erect and funnel-shaped. The capitulum margin of the latter species is highly folded. Colonies of *S. crassocaule* are flat with a short stalk.

Coral colonies of diameter 0.12–0.15 m were collected from the field and transferred to an acclimation tank in which the temperature was maintained at 24°C. The acclimation tank was furnished with two current generators which create consistent flow. These colonies were fed with resolvable food blocks (Reef Care, No. 134, Aquarium Pharmaceuticals). Three days were allowed for acclimation before the experiments.

A recirculating flow tank of capacity 75 l (3.2 m long, 0.15 m wide, 0.2 m high) was made according to Leverage (1976). The tank was filled with 70 l filtered seawater and a laboratory stirrer (Her-Cheng SC-VS35W) with a propeller (0.14 m diameter) was used to generate water flow. The flow velocity was controlled by a solid-state motor control and measured with an electromagnetic current meter (Kenek, VM-401H). Detector (sensor part  $\varnothing 8$  mm  $\times$  30 mm) of the current meter was placed 0.15 m upstream from the colony.

## 2.2. Flume experiments

During the experiment, a coral colony was transferred into the flow tank and fastened on an acrylic base. The base was supported by a tray filled with stainless steel balls on the surface to reduce friction. The acrylic base was connected to a suspended electronic balance (Yong-Ten HA-02) by a nylon line. When the coral colony experienced stress from the water flow, the acrylic base moved on the tray and transmitted the force to the suspended electronic balance via the nylon line. The drag forces induced by a coral colony at various flow velocities were measured with the balance. The drag forces were then standardized by dividing them by the initial projected colony area.

The coral was allowed 6 h for further acclimation before drag measurement and only colonies with fully expanded polyps were tested. Three colonies were tested for each species. Each colony was tested at flow velocities ranging from 0 to  $0.35 \text{ m s}^{-1}$  at an interval of  $0.05 \text{ m s}^{-1}$ .

Colony profiles at various flow velocities were photographed through the window of the tank using a camera. Since deflection of an organism in response to flowing water depends on its flexibility (Vogel, 1984), the flexibility of a coral colony is represented by the deflective angle of the colony at various flow velocities.

Projected colony areas perpendicular to the flow at various velocities were then photographed using an underwater camera (Nikonos-V) with a 20 mm lens. The photographs of projected colony area were traced and measured using a digitizer (Lab Visions LV-1) associated with a personal computer. Variations of colony area under various flow velocities were standardized by dividing the measured projected area by the initial projected colony area.

Drag coefficients of the three species were calculated from the drag measurements and projected colony areas, based on the equation:

$$C_D = 2D/(\rho S U^2)$$

where  $C_D$  is drag coefficient,  $D$  is drag force,  $\rho$  is density of fluid,  $S$  is projected colony area and  $U$  is velocity (Vogel, 1981).

## 2.3. Mechanical testing

The coral colonies were anaesthetized overnight in a sea water–20%  $\text{MgSO}_4 \cdot 7\text{H}_2\text{O}$  solution mixture (1:1) until polyps did not contract when pinched with a forceps (Koehl, 1982b). Strips of tissue were cut from the stalk of coral colonies with a slicing machine (Omas VS250) and prepared for mechanical tests.

Strips of tissue were stretched in a mechanical test system (MTS 810) that simultaneously printed the force-extension diagram on a plotter (X-Y recorder, Yokogawa 3025). The strain rate was controlled in  $\epsilon = 0.01 \text{ s}^{-1}$  (where  $\epsilon = \Delta L/L_o \cdot t$ ,  $\Delta L$  is the variation of length of the specimen at time  $t$ , and  $L_o$  is the original length of the specimen). Stress ( $\sigma$ ) and extension ratio ( $\lambda$ ) were calculated according to  $F/A$  ( $F$  is force and  $A$  is cross-sectional area) and  $\Delta L/L_o$ . Plots of stress versus extension ratio

were made. The slope of the straight portion of each stress-extension curve was taken to be the modulus of elasticity, a measure of stiffness (Koehl, 1982b).

### 3. Results

#### 3.1. Drag forces

The drag forces encountered by colonies of the three species under various flow velocities showed different patterns (Fig. 1). The drag forces of *Sarcophyton cinereum* and *S. crassaucle* were basically proportional to the square of flow velocity. However, the drag forces of *S. buitendijki* showed two distinct trends with the breaking point appearing at  $0.15 \text{ m s}^{-1}$ . Below this point, the drag forces increased rapidly with increasing flow velocities. While above this point, the drag forces increased slowly with flow velocities. The variation of drag force was also related to projected colony area and drag coefficient under various flow velocities.

The projected colony area of *Sarcophyton crassaucle* at various flow velocities remained roughly constant (Fig. 2). No significant difference was found between the mean colony area at a particular flow velocity and the initial colony area ( $t=1.093$ ,  $P>0.05$ ). The projected colony areas of *S. buitendijki* and *S. cinereum* increased with flow velocity initially, then reduced with increasing flow velocity. The upstream fringe

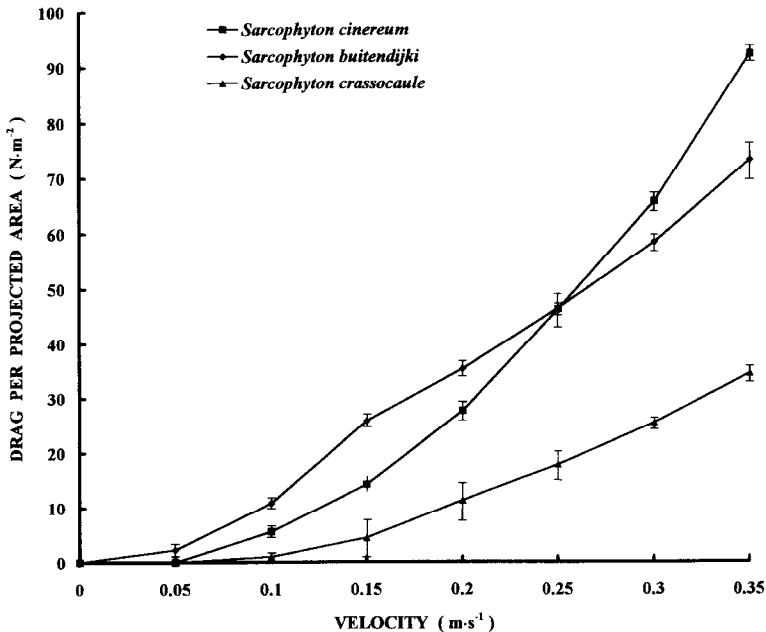


Fig. 1. Drag per projected area as a function of flow velocity for *Sarcophyton cinereum*, *S. buitendijki* and *S. crassaucle*.

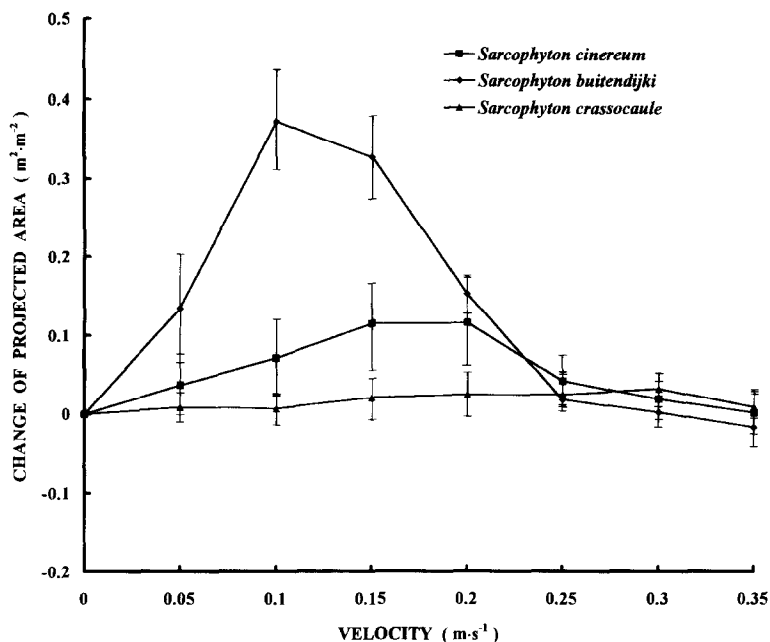


Fig. 2. Variation of projected area as a function of flow velocity for *Sarcophyton cinereum*, *S. buitendijki* and *S. crassocaule*.

of capitulum of *S. buitendijki* was lifted by flow and resulted in an increase of projected colony area, and the drag force increased rapidly from 0 to  $0.1 \text{ m s}^{-1}$ . The capitulum clumped and the stalk tended to orient parallel to the flow, which resulted in a reduction of projected colony area, and the drag force increased slowly above  $0.1 \text{ m s}^{-1}$ . The capitulum of *S. cinereum* showed no obvious variation with flow velocity, but the stalk was tilted with increasing flow velocity. The maximum projected colony area appeared during  $0.15\text{--}0.2 \text{ m s}^{-1}$ .

Variation of drag coefficient with flow velocity is related to the body shape of an organism (Vogel, 1981). *Sarcophyton crassocaule* exhibited no significant variation of drag coefficient with flow velocity (Fig. 3). The drag coefficient of *S. cinereum* increased with flow velocity (Fig. 3). The drag coefficient of *S. buitendijki* increased with flow velocity from 0 to  $0.15 \text{ m s}^{-1}$ , then reduced by collapsing the colony into more compact streamlining at  $>0.15 \text{ m s}^{-1}$ .

Morphological deformation of the three species at various flow velocities showed different patterns (Fig. 4). *Sarcophyton crassocaule* showed no obvious deflection at various flow velocities. The deflective angles of colony axes of *S. buitendijki* and *S. cinereum* increased with flow velocities, but the former deflected more readily than the latter. *S. cinereum* was tilted from  $20$  to  $70^\circ$  in the direction of water movement with increasing flow velocity. *S. buitendijki* deflected rapidly from 0 to  $0.15 \text{ m s}^{-1}$ , then slowly due to streamlining at flow velocities  $>0.15 \text{ m s}^{-1}$ . The results showed that *S. buitendijki* is the most flexible of the three species.

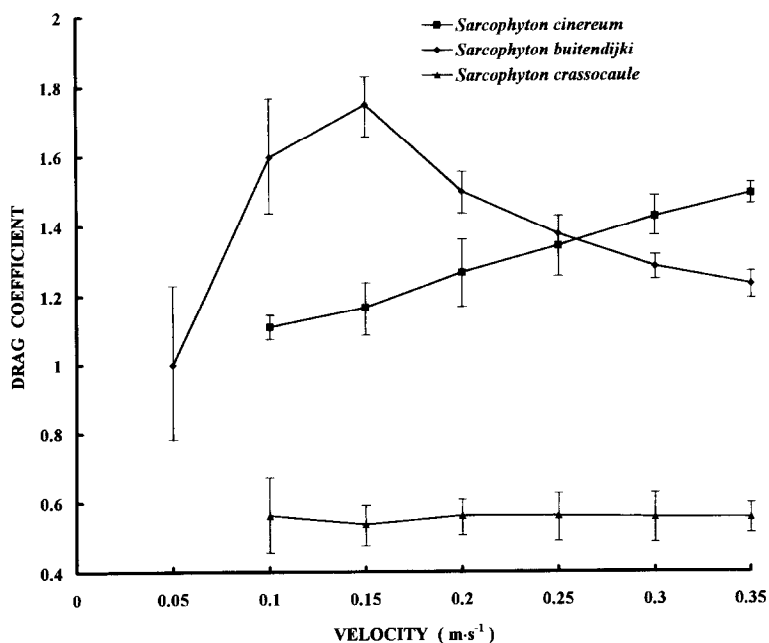


Fig. 3. Drag coefficient as a function of flow velocity for *Sarcophyton cinereum*, *S. buitendijki* and *S. crassocaula*.

### 3.2. Tensile strength

The stress-strain curves show that the stress of *Sarcophyton crassocaula* increased more rapidly with increasing strain than those of *S. cinereum* and *S. buitendijki* (Fig. 5). Hence the elastic modulus of *S. crassocaula* ( $E = 13.37 \pm 1.76 \text{ MN m}^{-2}$ ,  $n = 3$ ) is higher than those of *S. cinereum* ( $E = 8.50 \pm 1.18 \text{ MN m}^{-2}$ ,  $n = 3$ ) and *S. buitendijki* ( $E = 3.47 \pm 0.79 \text{ MN m}^{-2}$ ,  $n = 3$ ). Since tensile strength depends upon elastic modulus of the tissues, *S. crassocaula* has the highest stiffness, and *S. buitendijki* the lowest.

## 4. Discussion

The three *Sarcophyton* species revealed three different strategies to withstand drag force: flexibility, streamlining and stiffness. A flexible organism exposed to flow may minimize drag force by altering colony shape and reducing projected colony area (Vogel, 1984; Harvell and LaBarbera, 1985). The flexibility of *Sarcophyton buitendijki* colonies enables them to bend into a drag-reducing shape and orientation at higher velocities. The wake behind the colony is reduced and the drag coefficient is therefore reduced (Koehl, 1982a) as ambient flow tends to pass around the organism rather than to impinge on it (Wainwright and Koehl, 1976). The deformation or reorientation of an organism contributes to the variation of drag coefficient, and therefore, also contributes to the drag

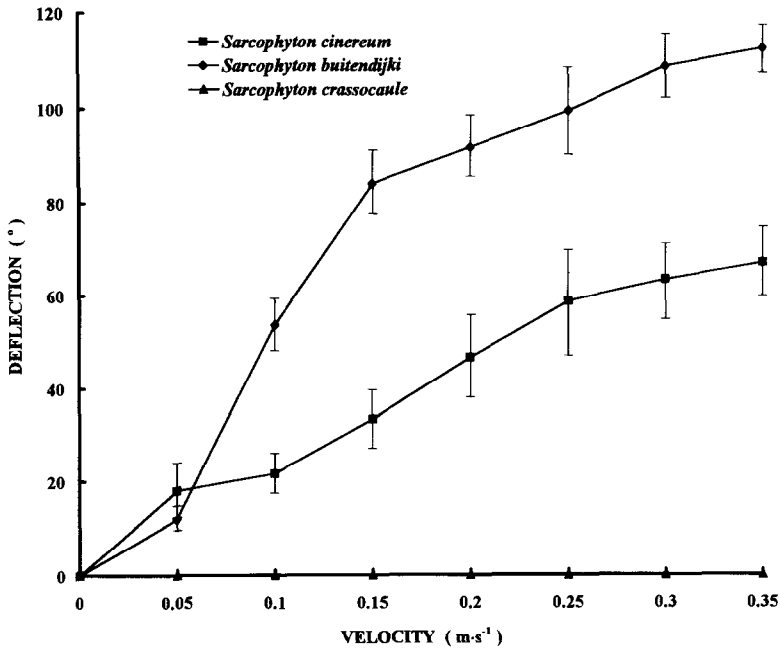


Fig. 4. Deflective angle of colony axis as a function of flow velocity for *Sarcophyton cinereum*, *S. buitendijki* and *S. crassocaula*.

forces experienced in flow (Sponaugle and LaBarbera, 1991; Dudgeon and Johnson, 1992). Flexibility acts to reduce the drag coefficient and the wake size behind the organism, thus the drag force can be reduced (Koehl, 1984).

Soft corals can minimize drag forces by lying within the boundary layer where the water velocities are lower than mainstream (Vogel, 1984). Colonies of *Sarcophyton crassocaula* are flat and they tend to live within the boundary layer. The flat colony also indicates that they are essentially streamlined. The high stiffness of *S. crassocaula* may allow them to retain the streamlining and to stay in the lower-velocity boundary layer.

Stiffness may also increase the capacity of an organism to withstand flow stresses (Koehl, 1979, 1982b; Vogel, 1988). *Sarcophyton cinereum* has intermediate flexibility and stiffness among the three species. Since the deformation of *S. cinereum* colonies results in no significant reduction of drag forces, this species may resist drags by stiffness rather than avoiding such forces by deformation.

Although both colonies of *Sarcophyton buitendijki* and *S. cinereum* are erect, they show different patterns in the relationship between drag forces and flow velocities. The drag force of *S. cinereum* increased with drag coefficient due to change in shape. A similar phenomenon was reported in two gorgonians by Sponaugle and LaBarbera (1991) where they suggested that a large reduction in the drag coefficient with increasing flow velocity that change in shape, rather than change in projected colony area, is primarily responsible for the reduction of drag force in a flexible colony. However, the flexibility of *S. buitendijki* colonies enables them to change shape readily.

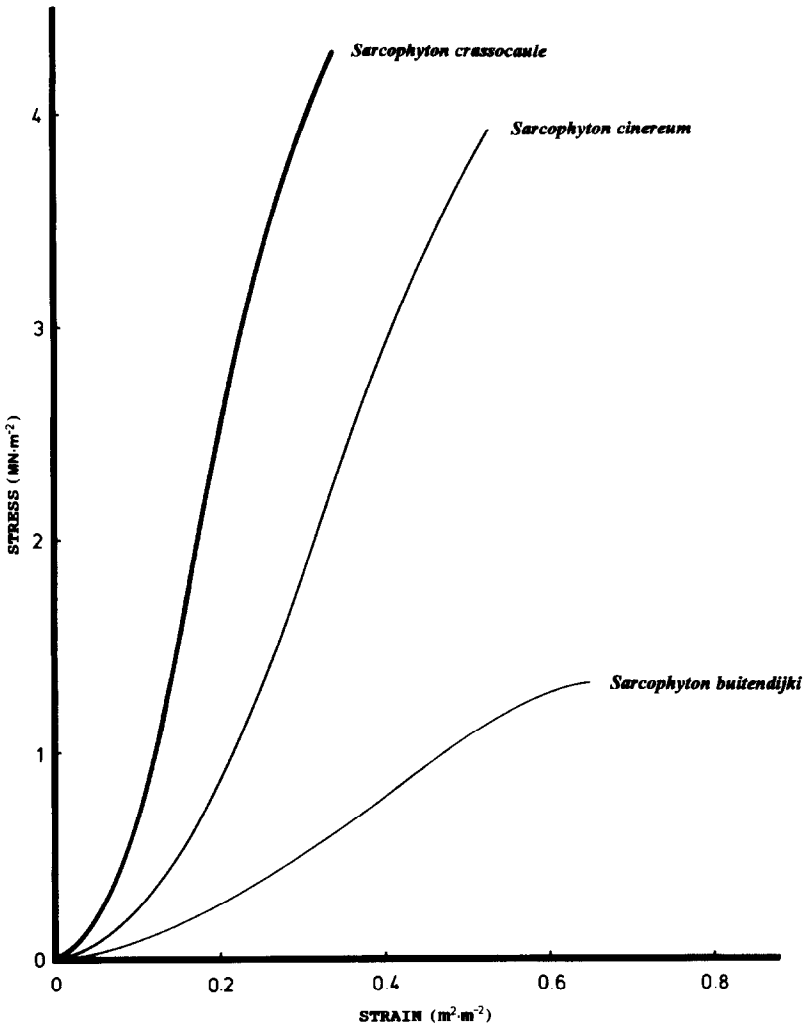


Fig. 5. Stress as a function of strain for the stalk tissue for *Sarcophyton cinereum*, *S. buitendijki* and *S. crassocaule*.

The drag force of *S. buitendijki* increased slowly whereas the projected colony area and drag coefficient reduced with flow velocity. The reduction in drag force of *S. buitendijki* is related to the reductions of projected colony area and drag coefficient due to change in shape.

The shape, size, flexibility, texture and behaviour of an organism affect the drag forces it encounters (Koehl, 1982a; Vogel, 1981). The three sympatric *Sarcophyton* species experience similar flow stresses, but they possess different morphological, mechanical and behavioural properties to reduce drag forces. *S. cinereum* likely reduces drag force by stiffness, *S. buitendijki* by flexibility and *S. crassocaule* by streamlining.



Hence various species coexisting in a same environment may adopt different strategies to reduce drag forces.

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