

Test Time Reduction for Scan-Designed Circuits by Sliding Compatibility[†]

Jau-Shien Chang Chen-Shang Lin

Department of Electrical Engineering
National Taiwan University
Taipei, Taiwan, R.O.C.

Abstract

A post generation method for test time reduction of scan-designed circuits is developed in this paper. Maximum overlapping condition between consecutive applied patterns is identified. The application of the condition facilitated with the developed active sliding compatibility process significantly reduces the number of test clocks. It is demonstrated that the test clocks can be reduced by 50% on average from given test sets. Further evaluation shows that, for parity-scan, the test clocks required by our developed method are only 41% of those in [3].

1 Introduction

To increase the fault coverage and the test quality of sequential circuits, the now popular scan design had been proposed [12]. The main feature of scan design is that, by scanning the flip-flops, the complicated sequential test problem is transformed into the much simpler combinational one, thereby the desirable test quality can be achieved. However, the necessity to shift test patterns and responses in the long scan chain may incur significant increase in test application time as well as test cost. To minimize the additional testing time while retaining test quality of scan design, various scan clock reduction methods have been proposed [1-5,7].

These previous works of test time reduction for scan-designed circuits can be divided into the following two general approaches: reduction *during test generation* or *after test generation*. To reduce the test application time during test generation, one way is to generate a combinational test set as compact as possible. Several effective techniques have been developed to generate such compacted test sets [6,8-9]. However, as pointed out in [3], test compaction alone is not enough to reduce test application time because further reductions can always be obtained by carefully rearranging the test patterns. Alternatively, in [4,7], the test generation is made to switch between scan-mode and nonscan-mode, and the scan mode is used only to achieve the required fault coverage. However, for circuits with many sequential hard-to-detected faults, the scan operations will occur frequently and result in test time worse than that of full-scan [4]. Moreover, complicated sequential test generation is involved in the process with the consequence of prolonged generation time.

The post generation approach is characterized by reducing scan requirements from a given test set. In [1,2], based on the assumption that scan-in and scan-out flip-flops are disjoint, each of the scan-in patterns is divided into several segments first. Then, the application of a test pattern to the CUT is invoked after scanning in only a segment but not necessarily a complete pattern. Thus, some faults originally detected by the later patterns may

become detectable by these segmented patterns and the test time can be reduced due to pattern removal. More elaborate pattern-overlapping techniques have also been developed in [7]. The overlapping of successive patterns are obtained by precisely controlling the scan operation through the utilization of don't-care bits in the scanned flip-flops. However, for a given test set with few don't-care bits, the overlapping often collapses due to the minor difference between successive patterns. In summary, the effectiveness of these previous works is heavily restricted by the characteristics of the given test set.

Recently, a novel idea, *parity-scan design*, has been proposed in [3], in which an extra parity output is introduced to the scanned flip-flops to enhance the observability. With this simple parity output, the scan operation can be eliminated if the fault effects can be easily observed and the content of flip-flops can be reused. To exploit the enhanced facility, direct test time reduction has been considered in [3] by generating a pattern with part of the previous pattern as the constraint so that a test set with highly overlapping patterns can be obtained. As shown in [3], the test time is reduced by 30% on average with the modified FAN [11]. However, the high overlapping among patterns is obtained at the expense of a much larger test set and as a result, even with the parity output, the reduction in test time is often inferior to that by compacting the test set for pure scan design. From the observations on these previous works, it can be seen that, in order to obtain consistently good results in test application time reduction, post generation approach with a compact test set is preferable.

We are going to show in this paper that more significant reduction of test clocks in scan-designed circuits can be achieved by the post generation approach. Namely, the reduction is performed after an initial test set is generated. We identify the condition which allows the *maximum overlapping* between successive applied patterns and then actively modify these patterns to exploit the overlapping without sacrificing fault coverage. The experimental results on 22 ISCAS89 benchmark circuits show that, for the test sets generated by PODEM, 50% test clocks in pure full-scan can be reduced on average. Furthermore, for the parity-scan design proposed in [3], our method needs only 52% test clock cycles of those generated in [3]. When the given test set is already compact, the improvement over [3] is even more significant, only 41% test clocks are required. The reduction is achieved strictly on the domain of combinational circuit.

The paper is organized as follows. Some notations and definitions about scan design are introduced in Section 2. The proposed Maximum Overlapping condition is described in Section 3. In Section 4, the active operation of sliding compatibility for maximum overlapping is introduced. Section 5 provides the Experimental Results. The Conclusions are given in the last Section.

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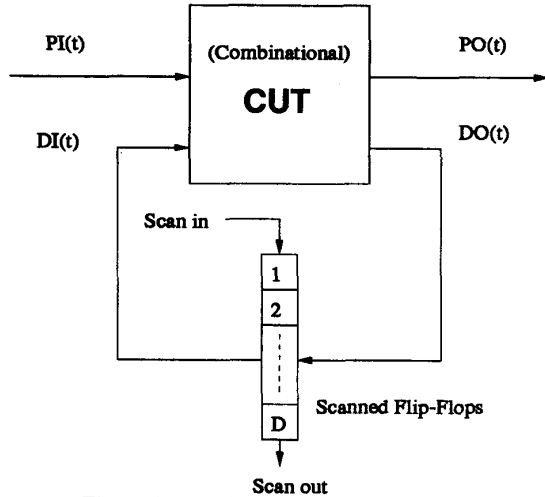


Fig. 1 A scan-designed sequential circuit

2 Scan Design

In this section, the full scan-designed circuits will be briefly discussed. Some notations and definitions useful for subsequent discussions will also be introduced.

For a scan-designed circuit as shown in Fig. 1, each test pattern t for the CUT (Circuit Under Test) consists of two parts: the part applied to PI denoted as $PI(t)$ and the other part for the FFs (Flip-Flops) as $DI(t)$. In the test application of t , $DI(t)$ must first be shifted into the scan path which generally consists of all FFs in the circuit. Let $RESP(t)$ be the response of CUT after applying t . $RESP(t)$ can be similarly divided into $PO(t)$ and $DO(t)$, where $PO(t)$ is the response appearing at PO and $DO(t)$ is that to be loaded into FFs. $DO(t)$ must also be shifted out of the scan path for observation, which may overlap with the scan-in of the next pattern.

Let T be the test set to be applied and D be the number of shifts for each pattern (in general, D is the number of scanned flip-flops), then total testing time, t_T , is

$$t_T = (|T| + 1) * D * S + |T| * C \quad (2.1)$$

where S and C are the periods of a shifting clock and system clock, respectively. Assuming $S = C$, t_T becomes

$$t_T = (|T| + 1) * D + |T| * S \quad (2.2)$$

The total test clocks of T for a scan-designed circuit, TTC , is then

$$TTC = (|T| + 1) * D + |T| \quad (2.3)$$

From (2.3), it can be seen that, to reduce the total test clocks, we can either compact the test set T as small as possible or shorten the number of shifts for each pattern. For test set compaction, there already exist effective tools such as COMPACTEST[9] and TSR[6]. At present, TSR has been adopted in our work. Therefore, in this paper, we will aim at how to reduce the number of test clocks on D . Note that we assume the scan-chain topology has been determined before test clock reduction.

3 Maximum Overlapping

Given a test set, the primary step of test clock reduction is to identify the maximum overlapping possible between two consecutive patterns without sacrificing fault coverage. In this section, the condition for *Maximum Overlapping* will be discussed.

Since the purpose of reduction is to use the current content of FFs as part of the next scan-in pattern, two types of overlapping are possible, either overlapping with the response of the previous pattern or the previous pattern itself. Both need some elaboration. In the first case, one must be sure that the content of FFs is not contaminated by the fault effect of all possible faults under consideration. And in the second case, the fault effect should be observed directly from primary outputs and the FFs retain the previous pattern by skipping the load response operation.

Two special cases for pattern overlapping have been proposed in [3]. Under the constraint that all the activated faults of the current applied pattern t_i can be observed at POs, the following two cases are accepted for reducing the test clocks of the next pattern t_{i+1} .

case (a) *Complete DO-reuse*: $DO(t_i) \equiv DI(t_{i+1})$,

case (b) *Complete DI-reuse*: $DI(t_i) \equiv DI(t_{i+1})$.

The ' \equiv ' above is the *compatible* relation. Two vectors are said to be compatible if all the corresponding bits are either of the same logic value or one of them is 'x' (don't care). For example, the two vectors, $v1 = (0x01)$ and $v2 = (010x)$, are compatible and denoted as $v1 \equiv v2$. When one of the above two cases is satisfied, the current content of FFs can be completely reused as part of t_{i+1} and the scan-in operation of t_{i+1} can be eliminated. However, the conditions used in [3] are clearly restrictive. The general conditions for maximum overlapping will be described next.

To allow maximum overlapping, we will first examine the conditions by which the content of FFs can be safely reused. As discussed in the beginning of this section, to reuse the DO-part, one must be sure that no fault effect will appear in FFs. In other words, the content of FFs must be the fault-free response to allow safely reuse. This is by no means trivial since the fault effect of some faults can only be observed after scanning out the content of FFs. Nevertheless, we generally need not scan out the whole chain to determine whether or not it is the fault-free response. This is stated in the following observation.

Observation 1 (DO-Reuse): *Under single fault assumption, after applying a pattern t to the CUT and loading its response $DO(t)$ into the scanned FFs, the presence of a detectable fault f of t can be determined from either POs or its first fault effect bit in $DO(t)$. Furthermore, if POs and the first fault effect bits of all detectable faults of t in $DO(t)$ have been observed to be fault-free, then these faults are not present and $DO(t)$ is the fault-free response.*

The implication of Observation 1 is that after examining a few possible fault-effect bits in $DO(t)$, the remaining fault-free response may provide an overlapping chance with the next pattern. From the observation, the number of bits to be shifted out after applying a pattern is then $MAX(MINBIT(f))$ for each detectable fault f by the pattern. This number can be easily determined by the fault simulation before actual test application. After shifting out this predetermined number of bits, it can be decided whether or not the remaining bits are fault-free and can be safely reused. For the example shown in Table 1, suppose three faults $\{f1, f2, f3\}$ are detected by applying pattern t and the fault-free $DO(t) = (1001010)$, by means of possible fault-effect bits computation in $DO(t)$, the faulty bit nearest to the scan-out pin is selected as $MINBIT(f)$. Since the maximum of $MINBIT$ is found to be 4, $DO(t)$ must be shifted out 4 bits before re-usage.

	DO(t)	MINBIT(f)
	7654321	
ff	1001010	-
f1	d001d10	3
f2	1d0d010	4
f3	1d0d0d0	2

ff: Fault Free response
d: denote the fault effect

Table 1. Example of MAX(MINBIT(f)) Computation

The DI-reuse condition is the same as described earlier and formally given as follows.

Observation 2 (DI-Reuse): *The current pattern in the FFs, $DI(t_i)$, may be part of $DI(t_{i+1})$ only if all the detected faults of t_i can be observed at POs alone.*

It can be seen that when fault effects must be observed from FFs, the DI-reuse can not be applied. The problem can be significantly alleviated if extra hardware is used to enhance observability such as that in parity-scan designed circuits[3].

The above two observations are the necessary conditions to reuse the current content of FFs. The following observation provides a sufficient condition for overlapping the next pattern with the current content of FFs, so that the test clocks can be reduced.

Observation 3 (Maximum Overlapping): *The current content of FFs, $SFF(t_i)$ ($DI(t_i)$ or $DO(t_i)$), may constitute part of $DI(t_{i+1})$ without sacrificing fault coverage if the conditions of Observations 1 or 2 are satisfied and $TAIL(SFF(t_i)) \equiv HEAD(DI(t_{i+1}))$, where $TAIL$ and $HEAD$ are the trailing and leading parts during scan, respectively.*

The last condition of Observation 3 requires only the trailing part of $SFF(t_i)$ is compatible with the leading part of $DI(t_{i+1})$ without explicitly specifying the size of parts. The condition is named *sliding compatibility* of $SFF(t_i)$ and $DI(t_{i+1})$. Sliding compatibility is the generalisation of complete compatibility for test clock reduction.

The extent of overlapping which can be actually achieved from the above observation depends on the ordering of scan chain. Although it is theoretically possible to rearrange scan path to obtain maximum reduction, physical constraints discourage such arbitrary rearrangement. Hence the aspect of rearrangement is not discussed and, in our experiment, the natural ordering of scan path is used.

Based on Observation 3, the process for maximum overlapping can be performed as follow. In the previous example in Table 1, after shifting 4 bits out of $DO(t) = (1001010)$, there are still 3 bits can be overlapped with the next pattern. In other words, three scan clocks can be reduced if the next pattern is compatible with $(zzzz100)$. To take fullest advantage of this situation, the next pattern can be chosen accordingly. When this is not possible, the next choice can be the one that is sliding compatible with $(zzzz100)$, i.e., compatible with $(zzzzz10)$ and then with $(zzzzzz1)$. Note that, with sliding compatibility, the extent of test clock reduction decreases step by step. In the extreme case, not even sliding compatibility is possible and regular scan operation must be performed. A more effective implementation of this process will be described in the next section.

4 Active Sliding Compatibility

The goal of maximum overlapping is to optimally reuse the current content of scanned FFs in the next scan-in operation. However, for a test set lack of sliding compatibility between patterns, the reduction on test clock will not be significant. It means that the effectiveness of maximum overlapping could be restricted by the nature of the given test set. Therefore, to further enhance the reuse in maximum overlapping, we propose the process, *Active Sliding Compatibility*, which actively modifies the test set for sliding compatibility and increase the chance of reuse while keeping the overall fault coverage intact.

The basic idea of active sliding compatibility is to take advantage of the over-specification property of the given test set. For example, for a pattern $t = (01111)$ in a test set T , the fault coverage of T may still keep intact when t is changed to $t' = (0x1x1)$. In this case, t is said to be *over-specified* in T and these bits changed from '0' or '1' to 'x' are said to be *raised*. Comparing t with t' , t' obviously has more chances to be compatible with any arbitrary vector than t . Thus, when trying to reuse the current contents of FFs for the scan-in of t , modifying t to t' would be a better choice.

In active sliding compatibility, for the next pattern to be scanned in, those sliding incompatible bits with the current contents of FFs will be modified (raised) to 'x' for re-usage. However, during raising these incompatible bits, it is essential to preserve the overall fault coverage, $DET(T, F)$. The following observation allows us to perform the raising operation while keeping the fault coverage intact[6]. Define $ESS_T(t, F)$, the *essential faults* of t , as the set of faults in F that can only be detected by t but not others in T .

Observation 4: *Given a fault set F and a test set T of F , for a pattern $t \in T$, if t is substituted by t' such that $DET(\{t'\}, F) \supseteq ESS_T(t, F)$, then $T' = T - \{t\} + \{t'\}$ has at least the same amount of fault coverage as T .*

The implication of Observation 4 is that active sliding compatibility can be performed by raising some bits of t while monitoring the detectability of $ESS_T(t, F)$. And, the detectability of $ESS_T(t, F)$ can easily verified by fault simulation.

Step	DI(t)	Contents 654321	Operation	$\equiv DI(t_1)$?
Init	t_1	101000	-	-
	t_2	010011	-	No
	t_3	111110	-	No
1	t_1	101000	-	-
	t_2	x1x010	bit raising	No
	t_3	1x1110	bit raising	No
2	t_1	x10100	shift out 1 bit	-
	t_2	010xx1	bit raising	No
	t_3	11x110	bit raising	No
3	t_1	xx1010	shift out 2 bits	-
	t_2	01xx11	bit raising	No
	t_3	111x10	bit raising	Yes

Table 2. Example of active sliding compatibility

With Observation 4, the brief procedure for maximum overlapping described at the last of Section 3 can be refined to the *active sliding compatibility* process for achieving more reductions on test clocks. The process is illustrated by the following example. As shown in Table 2, for

a test set $T = \{t_1, t_2, t_3\}$, after applying t_1 , active sliding compatibility is performed to select the next applied pattern. Only DI-reuse is considered in this example for simplicity. Initially, $DI(t_1)$, $DI(t_2)$ and $DI(t_3)$ are mutually incompatible. In step 1, after the raising operation on these incompatible bits, the DI-parts of the three patterns are still incompatible. Therefore, one shift out operation is performed on $DI(t_1)$. In step 2, after the $DI(t_1)$ is shifted out 1 bit, active operations for compatibility is performed on $DI(t_2)$ and $DI(t_3)$ again. Unfortunately, it also fails. In step 3, after the content of $DI(t_1)$ is shifted out one more bit, the DI-parts of t_1 and t_3 become compatible after raising. Thus, 4 scan clocks can be saved for the scan-in of t_3 . Without these active raising operations, only one scan clock (choosing t_2 as the next pattern) can be reduced in this example.

5 Experimental Results

To show the effectiveness of our method (ACT), these test clock reduction techniques proposed in this paper have been implemented on SUN4-SPARC2 workstation and 22 ISCAS'89 benchmark circuits are evaluated.

Ckts	SFF	PDM	TSR	PDM-P	TSR-P
s208	8	50	27	50	27
s298	14	51	25	51	24
s344	15	33	14	33	15
s349	15	33	14	33	15
s382	21	50	25	49	25
s386	6	97	63	92	63
s420	16	88	44	88	44
s444	21	47	25	47	25
s510	6	79	57	76	56
s526	21	98	50	97	50
s641	19	88	24	98	24
s713	19	88	24	85	24
s820	5	188	96	183	96
s832	5	180	97	182	96
s838	32	155	76	152	76
s953	6	109	76	115	77
s1196	17	222	124	232	126
s1238	17	230	133	234	129
s1423	74	126	32	118	32
s1488	6	176	104	183	106
s1494	6	185	102	175	103
s5378	179	425	109	415	111

SFF: number of scanned flip-flops
 * number of total flip-flops

Table 3. Test sets of ISCAS89 benchmark circuits

In Table 3, the number of Scanned Flip-Flops (SFF) of these circuits are shown. In addition, two initial test sets of these circuits are evaluated for both full-scan and parity-scan version. One initial test set is generated by a simple PODEM-like ATPG and the other is its highly compacted set by TSR[6]. These two test sets can be regarded as two extremes for an arbitrarily given test set. The sizes of these four different test sets, two for full scan and two for parity-scan[3], are also included in Table 3. For the test sets in PDM-P and TSR-P columns, they are generated in a similar way to PDM and TSR test sets except a parity-checking path for pseudo POs (i.e. scanned FFs) and an extra PARITY output are added during test generation. In Table 4 and 5, the test clock reduction results of ACT on the PDM, TSR, PDM-P, TSR-P test sets are shown.

The comparison of ACT with previous works are provided in Table 6.

In Table 4, the test clocks generated by ACT for PODEM and TSR test sets are given. The final results are shown in the ACT column and those only with sliding but without bit-raising operations are listed in the SLIDE column. The number after each datum is the normalized ratio with respect to pure full scan (FSCAN) of the given test set. For the PODEM test sets, by the sliding operation (SLIDE), 29% test clock reduction can be achieved on average as shown in the last row. It can be seen that SLIDE is more effective for those circuits with less scanned flip-flops such as s820, s832, s1488 and s1494. For those circuits with a large amount of scanned FFs such as s1494 and s5378, the reduction is less successful due to the difficulty of overlapping between successive scanned patterns. However, when bit-raising is added to increase the chance of overlapping, as shown in the ACT column, up to 46% and 65% reduction on test clocks for s1423 and s5378 can be obtained respectively. This shows the effectiveness of the proposed active sliding compatibility process. On average, by ACT, 50% of test clocks for FSCAN can be reduced. For the TSR test sets, although the test sets are much more compact than those of PODEM and hence there is less chance for overlapping, 27% reduction can still be achieved by our methods. When comparing the total test clocks of FSCAN for TSR test sets with those for PODEM test sets in the \sum / AVG row, less than 1/3 (38268/118036) of the test clocks are required, a very significant reduction on test clocks and test cost. It demonstrates that using a compact test set as the starting point of test clock reduction is worthwhile and the efforts on the additional test set compaction can be well-justified.

For the parity-scan designed circuits, the results of ACT on PODEM-P and TSR-P test sets are shown in Table 5. In comparison with Table 4, with the extra parity output, the average reduction ratio can be increased from 50% to 72% for PODEM test sets and from 27% to 53% for TSR test sets. This shows the positive effect of enhanced observability by the parity output. Note that, for these circuits with more scanned FFs such as s838, s1423 and s5378, the results of ACT on TSR and TSR-P test sets are quite close ((1163,1013), (2285,2086), (14252,14351)). The reason is as follows. Due to with a large number of FFs and compacted test sets, the fault effect of each fault in these circuits are more likely to reach many FFs and scan operations for each pattern generally can not be avoided. However, from Observation 1, we are able to observe the existence of these faults through a few shift-out operations almost as effective as adding an extra parity output. It suggests that, in those circuits with large number of flip-flops, it is more advantageous to use the proposed ACT starting from the compacted test set since it can accomplish almost the same amount of test clock reduction as the additional parity chain, albeit without any hardware overhead.

The comparison of ACT with the previous work, Parity-Scan[3], is shown in Table 6. The test clocks by [3] are listed in the PSCAN column. The results of ACT with the parity output are shown in the ACT-PDM(P) and ACT-TSR(P) column respectively, which are identical to Table 5. The number after each datum is the normalized ratio with respect to PSCAN. Comparing ACT-PDM(P) and PSCAN, except s1196 and s1238, our results are far superior to those of [3]. On average, the test clocks of ACT-PDM(P) are only 52% of those of PSCAN. It clearly shows effectiveness of the proposed active test clock reduction. In particular, for s1423 and s5378, 61% and 75% reduction can be achieved, even though the test set size used in [3] are approximately equal to that of the PODEM-P test set shown in Table 3. The result demonstrates the merit of

Ckts	PODEM test sets			TSR test sets		
	FSCAN	SLIDE	ACT	FSCAN	SLIDE	ACT
s208	458	301/0.66	220/0.48	251	198/0.79	182/0.73
s298	779	654/0.84	478/0.61	389	354/0.91	317/0.81
s344	543	471/0.87	360/0.66	239	225/0.94	224/0.94
s349	543	471/0.87	360/0.66	239	229/0.96	227/0.95
s382	1121	1001/0.89	728/0.65	571	535/0.94	504/0.88
s386	685	418/0.61	405/0.59	447	341/0.76	341/0.76
s420	1512	1110/0.73	582/0.38	764	638/0.84	431/0.56
s444	1055	937/0.89	638/0.60	571	545/0.95	448/0.78
s510	559	333/0.60	320/0.57	405	273/0.67	276/0.68
s526	2177	1905/0.88	1293/0.59	1121	1039/0.93	947/0.84
s641	1779	1277/0.72	645/0.36	499	458/0.92	370/0.74
s713	1779	1293/0.73	624/0.35	499	475/0.95	367/0.74
s820	1133	680/0.60	633/0.56	581	474/0.82	477/0.82
s832	1085	657/0.61	623/0.57	587	479/0.82	493/0.84
s838	5147	3667/0.71	1872/0.36	2540	2101/0.83	1163/0.46
s953	769	446/0.58	428/0.56	538	373/0.69	377/0.70
s1196	4013	1610/0.40	726/0.18	2249	1045/0.46	576/0.26
s1238	4157	1552/0.37	745/0.18	2411	1161/0.48	676/0.28
s1423	9524	8850/0.93	5109/0.54	2474	2429/0.98	2285/0.92
s1488	1238	747/0.60	711/0.57	734	587/0.80	587/0.80
s1494	1301	770/0.59	743/0.57	720	591/0.82	591/0.82
s5378	76679	69792/0.91	26535/0.35	19799	19618/0.99	14252/0.73
Σ /AVG	118036/1.00	98942/0.71	44778/0.50	38628/1.00	34168/0.83	26111/0.73

FSCAN: test clocks of pure Full Scan
SLIDE: ACT without bit-raising
ACT: Active Sliding Compatibility technique

Table 4. Results of test clock reduction by ACT

post generation approach of test clock reduction. It is also interesting to compare PSCAN with ACT-TSR(P). In each evaluated case, the result of ACT-TSR(P) is far better than that of PSCAN. The average ratio of test clocks is only 41%. Recall that, in [3], the test sets are generated by preserving as more common parts as possible among patterns to increase the chance of overlapping. Evidently, the compactness of the generated test set is sacrificed. This comparison result clearly shows that sacrificing the compactness of the test set for overlapping is not worthwhile and a compact test set is desired for test clock reduction in scanned design.

In the last column of Table 6, the CPU-time for ACT-PDM(P) is shown. Except s5378, all the examples can be completed in one minute. For s5378, due to its circuit size, large test set and scanned FFs, more CPU-time, albeit not prohibitively long, is required. For ACT-TSR(P), because the test sets are much more compact than those of ACT-PDM(P), the CPU-time is far less than that shown in the Table. For example, in ACT-TSR(P), the CPU-time for s5378 is only 448 seconds.

6 Conclusions

Test time reduction for scan-designed circuits has been investigated in this paper. To reduce the lengthy shifting operations in the long scan path, post generation method to optimally reuse the contents of the scanned flip-flops have been developed. From the experimental results on 22 ISCAS89 benchmark circuits, up to 50% test clocks can be reduced on average by the proposed method. Furthermore, when the parity output is included in the scan-designed CUT, the resultant test clocks by ACT have been only 41% of those in [3]. It has been reported that by switching be-

tween scan-mode and nonscan-mode, further reduction on test clock cycles are possible in pure scan designed circuits. However, a sequential circuit test generation will then be required and the test generation time will be substantially increased. To retain the advantage of simple combinational test generation of scan-designed circuits, the mode-switching is not performed in this work.

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Ckts	PODEM-P test sets			TSR-P test sets		
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s208	458	296/0.65	222/0.48	251	198/0.79	183/0.73
s298	779	534/0.69	241/0.31	374	282/0.75	171/0.46
s344	543	409/0.75	247/0.45	255	213/0.84	191/0.75
s349	543	409/0.75	247/0.45	255	213/0.84	191/0.75
s382	1099	865/0.79	465/0.42	571	485/0.85	372/0.65
s386	650	198/0.30	180/0.28	447	152/0.34	153/0.34
s420	1512	982/0.65	415/0.27	764	601/0.79	366/0.48
s444	1055	872/0.83	381/0.36	571	495/0.87	344/0.60
s510	538	161/0.30	161/0.30	398	156/0.39	155/0.39
s526	2155	1757/0.82	556/0.26	1121	967/0.86	538/0.48
s641	1979	1168/0.59	329/0.17	499	406/0.81	265/0.53
s713	1719	1042/0.61	306/0.18	499	428/0.86	289/0.58
s820	1103	249/0.23	252/0.23	581	169/0.29	167/0.29
s832	1097	264/0.24	263/0.24	581	174/0.30	183/0.31
s838	5048	2918/0.58	1248/0.25	2540	1896/0.75	1013/0.40
s953	811	236/0.29	211/0.26	545	165/0.30	165/0.30
s1196	4193	1180/0.28	404/0.10	2285	575/0.25	278/0.12
s1238	4229	1170/0.28	408/0.10	2339	617/0.26	285/0.12
s1423	8924	7919/0.89	3041/0.34	2474	2324/0.94	2086/0.84
s1488	1287	313/0.24	296/0.23	748	221/0.30	221/0.30
s1494	1231	293/0.24	279/0.23	727	207/0.28	207/0.28
s5378	74879	60835/0.81	19563/0.26	20159	19363/0.96	14351/0.71
Σ /AVG	115832/1.00	84070/0.54	29715/0.28	38984/1.00	30307/0.62	22174/0.47

Table 5. Results of test clock reduction by ACT with PARITY output

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Ckts	PSCAN[3]	ACT-PDM(P)	ACT-TSR(P)	TIME
s208	279	222/0.80	183/0.66	2.0
s298	495	241/0.49	171/0.35	3.0
s344	461	247/0.54	191/0.41	3.0
s349	443	247/0.56	191/0.43	3.0
s382	828	465/0.56	372/0.45	4.0
s386	380	180/0.47	153/0.40	5.0
s420	1296	415/0.32	366/0.28	7.0
s444	936	381/0.41	344/0.37	5.0
s510	354	161/0.45	155/0.44	6.0
s526	1707	556/0.33	538/0.32	10.0
s641	579	329/0.57	265/0.46	12.8
s713	729	306/0.42	289/0.40	12.1
s820	487	252/0.52	167/0.34	20.1
s832	471	263/0.56	183/0.39	20.7
s838	5602	1248/0.22	1013/0.18	30.2
s953*	2391	211/0.09	165/0.07	16.3
s1196	359	404/1.13	278/0.77	40.1
s1238	351	408/1.16	285/0.81	44.7
s1423	7894	3041/0.39	2086/0.26	60.2
s1488	617	296/0.48	221/0.36	36.8
s1494	702	279/0.40	207/0.29	35.0
s5378	76739	19563/0.25	14351/0.19	1492.0
Σ	101709	29504	22009	-
AVG	1.0	0.52	0.41	-

ACT-PDM(P): results of ACT on PDM-P test sets
 ACT-TSR(P): results of ACT on TSR-P test sets
 TIME: CPU time (sec) of ACT-PDM(P) on SUN4-SPARC2
 *: removed from comparison due to different no. of SFFs

Table 6. Comparison of ACT with PARITY-SCAN[3]